

Quick Start Guide MicroHAWK ID-20 / ID-30 / ID-40



MICROSCAN

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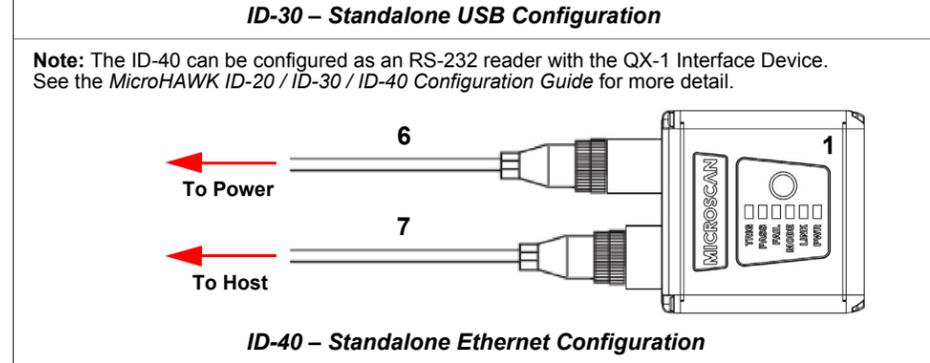
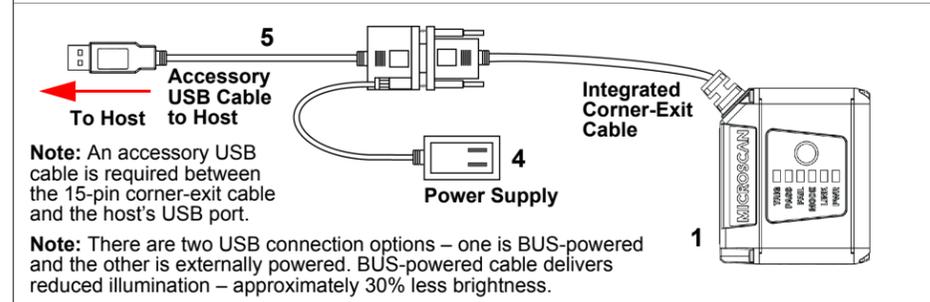
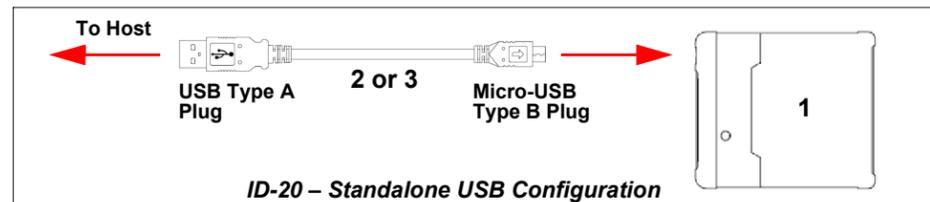
P/N 83-9137234-02 Rev C

Step 1 — Check Hardware

Note: Full configuration diagrams are available in the *MicroHAWK ID-20 / ID-30 / ID-40 Configuration Guide*.

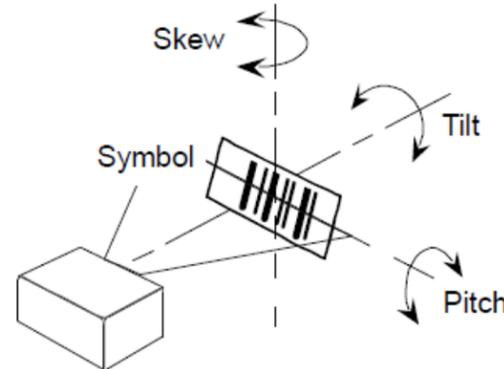
Item	Description	Part Number
1	MicroHAWK ID-20, MicroHAWK ID-30, or MicroHAWK ID-40	7AXY-YZZZ-LPPP
2	Cable, USB A to Micro B, 6 ft., ID-20	61-9000034-01
3	Cable, USB A to Micro B, 3 ft., ID-20	61-9000045-01
4	Power Supply, 5V	97-9000006-01
5	Cable, DB15 to Ext. Power/USB, ID-30	61-9000038-01
6	Power Supply, 100-240VAC, +24VDC, M12 12-Pin Socket	97-000012-01
7	Cordset, Host, Ethernet, M12 8-Pin Plug (Screw-On) to RJ45, 1 m.	61-000160-03

Step 2 — Connect the System



Step 3 — Mount and Position the Reader

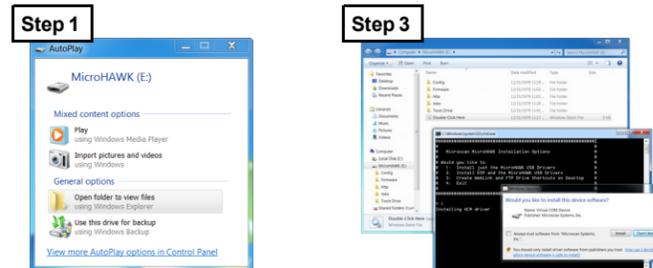
- Position the reader several inches from the symbol. You may need to reposition the reader a few times to find the ideal distance.
 - Tip the reader relative to the symbol to avoid the glare of direct (specular) reflection.
 - Symbols can be rotated (tilted) at any angle; however, for best results symbols should be aligned with the field of view. In the case of linear symbols, aligning the bars in the direction of their movement (ladder orientation) will minimize the chances of blurring and will result in more consistent decodes.
- Important:** Avoid excessive skew or pitch. Maximum skew is $\pm 30^\circ$; maximum pitch is $\pm 30^\circ$. The illustration below shows approximate skew axis, pitch axis, and tilt axis.



Step 4 — Install WebLink Drivers (ID-20 and ID-30)

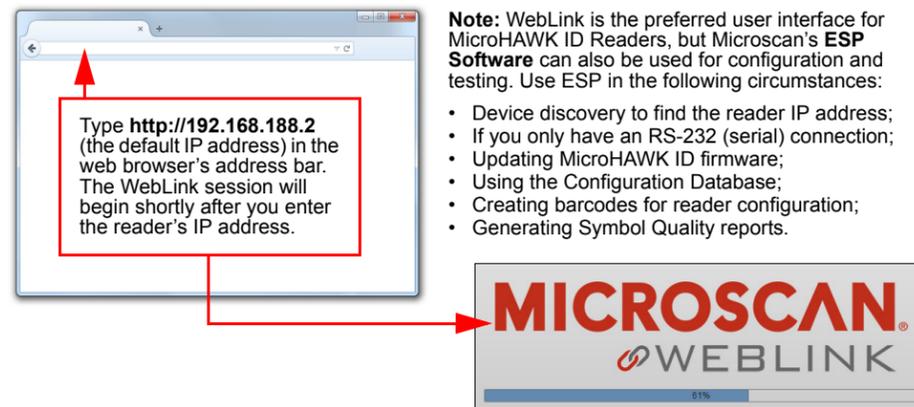
- Plug the reader into a USB port and wait for the **AutoPlay** dialog to appear.
- Click **Open folder to view files** and double-click the **Double-Click Here.bat** batch file.
- At the command prompt, select **option 1** and then type **Enter**. **VCOM** and **USBLAN** drivers are installed.
- At the command prompt, select **option 2** to install the **WebLink** and **FTP** drive shortcuts. **WebLink** and **MicroHAWK FTP** drive shortcut icons will appear on the desktop.
- When installation of the drivers and shortcuts is complete, unplug the reader from the USB port.
- Re-plug the reader into the USB port and wait for the reader to reboot and to enter read mode (**LEDs ON**).
- Double-click the **WebLink** desktop shortcut. **WebLink** will load and start (See **Step 5 – Connect to WebLink**.)
- Double-click the **FTP** drive shortcut and log in with username: **target** and password: **password**.
- The **FTP** drive is opened so you can access additional resources and installers in the **Tools and Documentation** folder.

You are now ready to use the MicroHAWK ID-20 or ID-30 with **WebLink**.



Step 5 — Connect to WebLink (ID-20 and ID-30)

When you double-click the **WebLink** desktop shortcut or enter the reader's IP address directly in the address bar of your web browser, **WebLink** will load and start.



Step 6 — Connect to WebLink (ID-40)

MicroHAWK ID-40 (Static Connection)

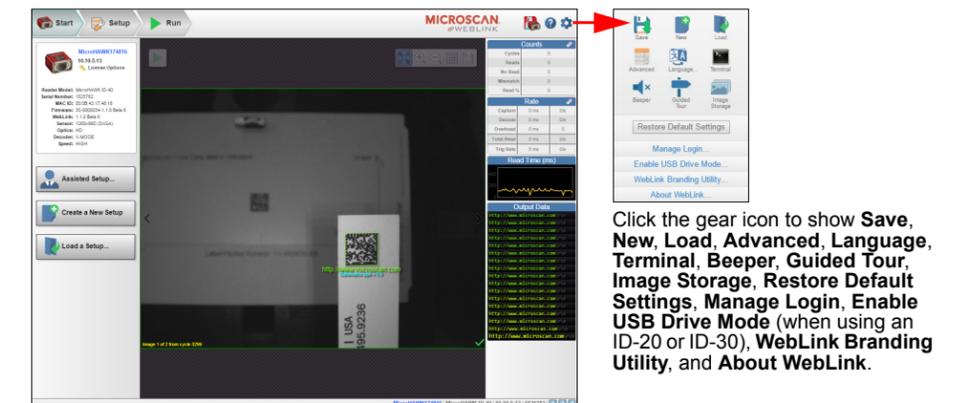
- Navigate to **Control Panel > Network and Sharing Center** on your PC.
- Click **Local Area Connection 4**. In the **Status** dialog, click **Properties**.
- In the **Local Area Connection Properties** dialog, select **Internet Protocol Version 4 (TCP/IPv4)** and click **Properties** again. Set your PC to a **192.168.188.X** IP address (**192.168.188.5**, for example).
- Click **OK**.
- Open a web browser and type the reader's default IP address (**http://192.168.188.2**) in the web browser's address bar. The reader will connect to **WebLink**.

MicroHAWK ID-40 (DHCP Network Connection)

- Plug your reader into the your network adapter.
- Open **ESP Software** and connect to the **MicroHAWK ID-40** via **Ethernet TCP/IP**.
- Click **Search** to find the reader. When the reader appears in the field below the **Search** and **Send** buttons, select it.
- Change the reader from **Static** to **DHCP** and click **Send and Save**. The camera will reboot and **ESP** will search for the reader again.
- When the ID-40 is found, note the new IP address that is generated.
- Open a browser and type the new IP address. **WebLink** will load.

Step 7 — Explore the Start View

The **Start** view is the initial view you will see when the **WebLink** session begins. The connected reader is shown, along with its **user-defined name** (must be **19** characters or fewer), **IP address**, **Reader Model**, **Serial Number**, **MAC ID**, **Firmware Version**, **Sensor**, **Optics**, **Decoder**, and **Speed**. This view allows you to choose **Assisted Setup**, to **Create a New Setup**, or to **Load a Setup**.



Refer to *WebLink Help* for information about **Advanced Settings** and **Terminal** functionality.

Step 8 — Create a New Setup or Load an Existing Setup

Assisted Setup

When you click the **Assisted Setup** button in the **Start** view, a dialog will appear asking you a series of application-based questions. Based on your answers, **WebLink** generates your initial setup automatically. Once the setup is created, you can fine-tune its parameters in the **Setup** view.

Create a New Setup

The **Start** view also allows you to create a **New Setup** without using **Assisted Setup**. When you click the **Create a New Setup** button, **WebLink** searches for any differences from default in the reader parameters. If no differences from default are found, you will see the **Setup** view. If differences from default are found, an alert will appear asking if you want to restore default settings.

Load a Setup

Select **Load Setup** to load an existing **.json** **WebLink** setup file. You can also load an **.esp** or **.txt** file from Microscan's **ESP Software**.



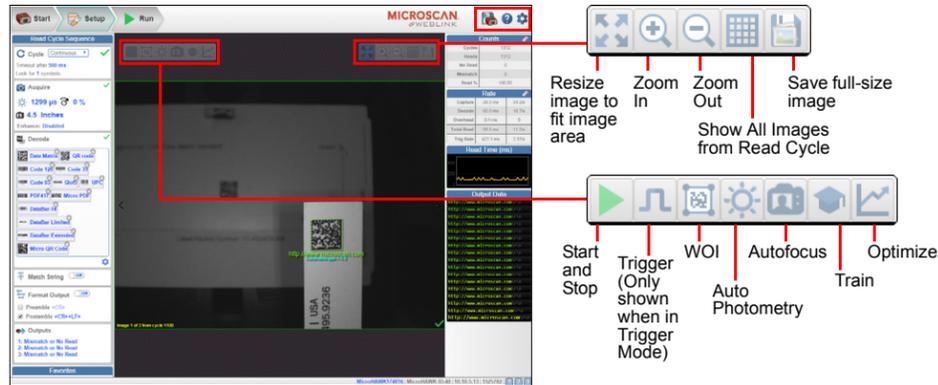
Step 9 — Explore the Setup View

The **Setup** view allows you to configure all aspects of a setup. Multiple discrete sections of the interface give you the ability to set **Cycle**, **Acquire**, **Decode**, **Match String**, **Format Output**, **Output** parameters, and **Favorites**.

Clicking the **Save** icon at the upper right saves current settings to the reader's flash memory so the settings will be available when the reader is rebooted.

The **question mark** icon at the upper right opens **WebLink Help**.

The **gear** icon at the upper right brings up the **Application Settings** menu.



Step 10 — Configure Read Cycle Settings

The **Cycle** section of the **Setup** view allows you to modify the trigger, determine the number of symbols for the reader to expect, and set **Read Cycle Timeout**. A dropdown menu of various Cycle types provides a variety of options, each with configurable parameters.

Presentation

This mode uses **Continuous Read Auto** along with **Continuous Capture Mode** and a **Timeout at End of Read Cycle**. **Green Flash Mode** is set to **Static Presentation** and the **Green Flash Duration** is set to **1 second**.

Continuous

This mode allows you to set the **Read Cycle Timeout** and the expected **Number of Symbols** from **1 to 100**.

Triggered

This mode sets the read cycle to **Serial Data and Edge**, **End of Read Cycle** is set to **Timeout or New Trigger**, and **Capture Mode** is set to **Rapid Capture** with **1 capture**. You can adjust the **Serial Trigger**, **Trigger Delay**, **Timeout**, and **Number of Symbols**.

Start / Stop

This mode uses **External Level** with a **Read Cycle Timeout** and **Continuous Capture**, allowing you to set **Leading Edge** and **Trailing Edge** as well as the **Serial Trigger** and the **Start and Stop Characters**. When **Serial Trigger** is set to **Off**, the start and stop characters are set to **NULL**, meaning that the trigger is disabled. When **Serial Trigger** is set to **On**, the start and stop characters are set to **S** and **E**. When the trigger button is clicked, it will use the current start and stop non-delimited triggers.

Custom

This mode allows you a wider variety of read cycle scenarios, including **Continuous Read Auto**. Use this mode to select **Trigger** mode and to set **Serial Trigger Character** and **Trigger Delay**; to select **Capture Mode** and to set **Number of Captures**, **Rapid Capture Mode**, and **Delay between Images**; and to select the **End Cycle On** setting as well as **Timeout** and **Number of Symbols**.

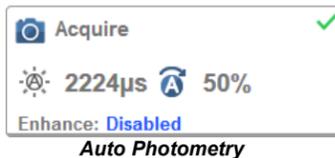
Step 11 — Configure Acquire Settings

Acquire settings allow you to set **Exposure** and **Gain** (signified by the dial and right-pointing arrow icon). Clicking any of these settings will cause a control to appear, allowing you to modify that setting. Settings take effect immediately.

Important: See *WebLink Help* for detailed information about **Autofocus** and **Spot Focus** functionality.



When **Auto Photometry** is enabled instead of **Standard**, Exposure and Gain are read-only. The **A** shown on the sun and dial icons signifies that **Auto Photometry** is enabled. Auto Photometry constantly determines the best Exposure and Gain settings during each read cycle.



Step 12 — Configure Symbology Settings

Clicking the **gear icon** at the bottom of the **Decode** section brings up **Symbology Settings**. This allows you to configure every parameter for every available code type.

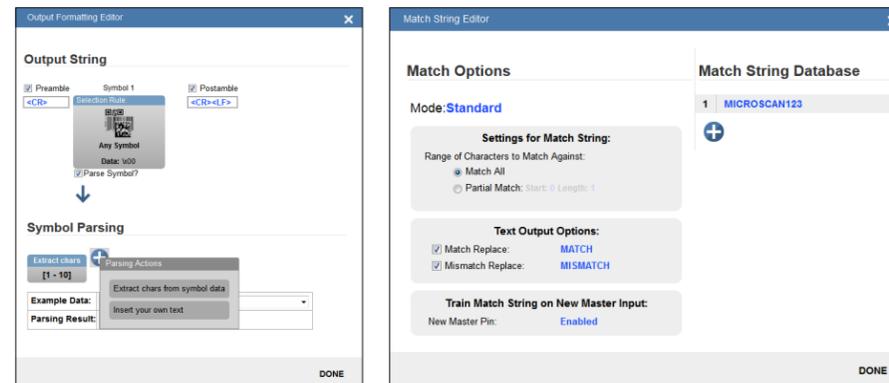
Symbology Settings		
Data Matrix	ECC 200 Status	Enabled
Code 128	ECC 000 Status	Disabled
Code 39	ECC 050 Status	Disabled
Codabar	ECC 080 Status	Disabled
Code 93	ECC 100 Status	Disabled
Interleaved 2 of 5	ECC 140 Status	Disabled
UPC/EAN	ECC 120 Status	Disabled
PDF417	ECC 130 Status	Disabled
Micro PDF417		
BC412		
Pharmacode		
DataBar Expanded		
Postal Symbologies		

Data Matrix error correction parameters are shown in this example, but you can configure any parameter for any of the code types supported by WebLink. All parameter changes for all code types take effect immediately.

Step 13 — Format Output and Configure Match String

Format Output, when enabled in the **Setup View**, allows you to determine the many ways in which barcode data can be formatted and parsed before it is output as a data string. You can also set **Preamble** and **Postamble** in this dialog.

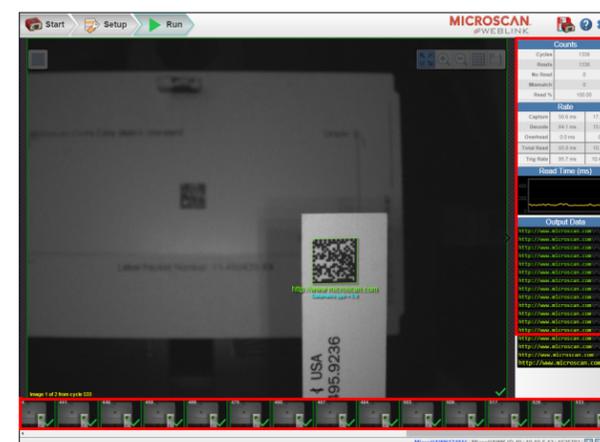
Match Options and **Match String Database**, accessible by clicking the **Match String** section in the **Setup View**, allow you to set the match code mode, text output, new master, and match string database.



Note: See *WebLink Help* for information about how to configure output settings.

Step 14 — Run the Application

In the **Run** view, you can observe the progress of the setup as it follows the parameters you have defined. The right pane of the UI shows **Counts** for **Inspected**, **Passed**, **No-Read**, and **Mismatch**, as well as **Read Rate**, **Reads per Second**, **Read Time** (shown numerically and visually), and **Output Data**. A "filmstrip" in the bottom pane shows each image capture with a **green check mark** for good reads and a **red x** for No-Reads.



Power Requirements and Pin Assignments

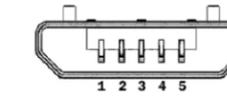
MicroHAWK ID-20: 5VDC ± 5%; 350mA at 5VDC (typ.)

MicroHAWK ID-30: 5V ± 5%; 600mA at 5VDC (typ.)

MicroHAWK ID-40: 4.75V – 30V; 150mA at 24VDC (typ.)

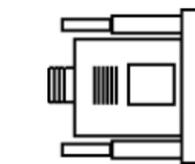
Important: See the *MicroHAWK ID-20 / ID-30 / ID-40 User Manual* for information about Microscan's **Isolation Mounting Kit (P/N 98-9000064-01)** to eliminate ground loops or other external electrical noise through your MicroHAWK ID-30 or ID-40 reader.

MicroHAWK ID-20 Micro-USB Type B Socket



Pin	Function
1	Vbus (5V)
2	D-
3	D+
4	N/C
5	Ground

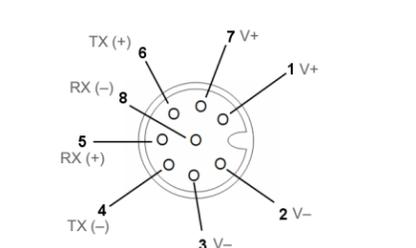
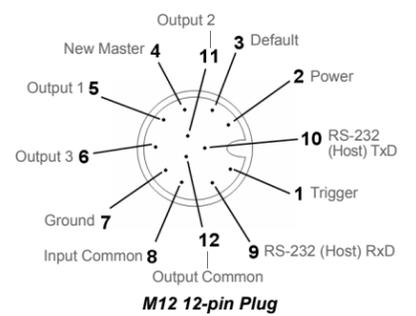
MicroHAWK ID-30 High-Density 15-Pin Dsub USB/Serial Socket



Pin	Function
1	+5VDC
2	TX232
3	RX232
4	GND
5	D+
6	N/C
7	Output 1+
8	Default+
9	Trigger+
10	D-
11	Output 3+
12	Input+ (New Master+)
13	Chassis
14	Output 2+
15	Vbus

Note: An accessory cable is required between the ID-30's 15-pin corner-exit cable and the host's USB port.

MicroHAWK ID-40 M12 Connectors



MicroHAWK ID Part Numbers

MicroHAWK ID part numbers follow the format **7ABX-YZZZ-LPPP**.

7 = MicroHAWK.

Example Part Number: 7312-2000-1005

Description: MicroHAWK ID-30, Auto ID, IP54 Enclosure, 5V, USB, SXGA 1.2 Megapixel, Mono, High Density, Autofocus, Red Outer LEDs, High Speed X-Mode Decoder.

(A) Model

- 1: Engine, No Case, USB
- 2: ID-20, IP40 Case, USB
- 3: ID-30, IP54 Case, 5V, USB
- 4: ID-40, IP65 Case, 24V, Ethernet

(B) Software

- 1: Auto ID

(X) Sensor

- 1: WVGA 0.3 Megapixel, Mono
- 2: SXGA, 1.2 Megapixel, Mono
- 3: QSXGA, 5 Megapixel, Color

(Y) Optics

- 0: Custom
- 1: Standard Density
- 2: High Density

(ZZZ) Focus Distance

- 000: Autofocus
- 050: 50 mm = 1.96 in.
- 064: 64 mm = 2.51 in.
- 081: 81 mm = 3.18 in.
- 102: 102 mm = 4.02 in.
- 133: 133 mm = 5.23 in.
- 190: 190 mm = 7.48 in.
- 300: 300 mm = 11.81 in.

(L) Outer LED Color

- 0: N/A (Engine and ID-20)
- 1: Red
- 2: White

(PPP) Speed and Decoder

- 000: Standard Speed, 1D Decoder
- 001: High Speed, 1D Decoder
- 002: Standard Speed, 1D/2D Decoder
- 003: Standard Speed, X-Mode Decoder
- 004: High Speed, 1D/2D Decoder
- 005: High Speed, X-Mode Decoder

Notes:

- (A) **Model:** The MicroHAWK Engine is available for OEM-certified partners only.
- (L) **Outer LED Color:** Outer LEDs provide extra illumination. Base level illumination included with all readers.
- (PPP) **Speed and Decoder:** 1D omnidirectional decoding functionality is included with all readers. The 1D/2D Decoder option is useful for printed labels. X-Mode is the full decoder package for 1D, 2D, DPM, and damaged symbols.
- Field Upgrades:** Not available for optics or illumination due to factory settings for optical alignment, LED balancing, and sealing for IP enclosure rating. However, the reader's speed and decoder version are field-upgradeable via licenses.